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SPIE International Symposium on

Optomechatronic Technologies (ISOT 2005)

5–7 December 2005

Sapporo Convention Center
Sapporo, Japan

Symposium Chair: Shun'ichi Kaneko, Hokkaido Univ. (Japan)

Actuators and Manipulation

Sensors and Instrumentation

**Micro/Nano Devices
and Components**

Machine Vision

Systems Control

Cooperating Organizations:

**Institute of Control, Automation,
and System Engineers (ICASE, Korea)**

Japan Optomechatronics Association (JOEM, Japan)



The International Society
for Optical Engineering



SPIE International Symposium on **Optomechatronic Technologies** (ISOT 2005)

5-7 December 2005
Sapporo Convention Center, Sapporo, Japan

Symposium Co-chairs:

Hyung Suck Cho, Korea Advanced Institute of Science and Technology (South Korea)

George K. Knopf, The Univ. of Western Ontario (Canada)

Toru Yoshizawa, Mitutoyo Corp. (Japan) and Tokyo Univ. A&T (Japan)

Rainer Tutsch, Technische Univ. Braunschweig (Germany)

Jonathan Kofman, Univ. of Waterloo (Canada)

Cooperating Organizations:

Institute of Control, Automation, and System Engineers (ICASE, Korea)

Japan Optomechatronics Association (JOEM, Japan)

In recent years, most engineered products, processes, and systems have evolved toward high functionality, flexibility, intelligence, and small scale. Moreover, the close relationship between optical and mechatronic engineering has had the effect of both enhancing and multiplying device and application functionality.

Optomechatronic Technologies 2005 will bring together you and other scholars, researchers and engineers working in this highly interdisciplinary field. There will be many opportunities to discuss the latest developments and trends in optomechatronics, as well as share your research, experiences and views with colleagues. Don't miss the opportunity to broaden your own body of work and help advance the exciting new engineering field of optomechatronic technology.

We welcome your participation!

Shun'ichi Kaneko,
Hokkaido Univ. (Japan)
Symposium Chair



Coinciding with the 100th anniversary of Albert Einstein's "Miraculous Year," the events of the World Year of Physics 2005 aim to raise worldwide public awareness for physics and more generally for physical sciences.

SPIE would like to express its deepest appreciation to the symposium chairs, conference chairs, and program committees who have so generously given of their time and advice to make this symposium possible. The symposium, like our other conferences and activities, would not be possible without the dedicated contribution of our participants and members.

SPIE's Event Project Manager for this symposium is Marilyn Gorsuch. For information about the technical program, email: meetinginfo@spie.org.

All papers from this program will be published in the SPIE Digital Library.

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Optomechatronic Actuators and Manipulation (JOM101)

Conference Chair: **Kee S. Moon**, Michigan Technological Univ.

Cochairs: **Rainer Tutsch**, Technische Univ. Braunschweig (Germany); **Bijoy K. Ghosh**, Washington Univ.; **Toru Yoshizawa**, Mitutoyo Corp. (Japan) and Tokyo Univ. A&T (Japan)

Program Committee: **Masaaki Adachi**, Kanazawa Univ. (Japan); **Ridha Ben Mrad**, Univ. of Toronto (Canada); **Young June Cho**, Korea Institute of Industrial Technology (South Korea); **David W. Greve**, Carnegie Mellon Univ.; **Dae Hwa Jeong**, LG Electronics Inc. (South Korea); **Timothy P. Kurzweg**, Drexel Univ.; **Sung-Q Lee**, Electronics and Telecommunications Research Institute (South Korea); **Miguel Levy**, Michigan Technological Univ.; **Michael Nahum**, Micro Encoder Inc.; **Takanori Nomura**, Wakayama Univ. (Japan); **Yukitoshi Otani**, Tokyo Univ. of Agriculture and Technology (Japan); **Heung K. Park**, Hyundai Electronics Industries Co., Ltd. (South Korea); **Young Soo Park**, Argonne National Lab.; **Sergey S. Sarkisov**, Alabama A&M Univ.

There has been a rapid growth in actuation and manipulation research in the past few years. Many novel materials, architectures, and applications have been proposed, built, and studied. The goal of this conference is to keep a record of the state-of-the-art research in this fast moving area. This conference is designed to fulfill the need for closer collaboration between researchers, academics, manufacturers, and end users by bringing them together in a single forum to interact, exchange technical knowledge, and discuss their experiences. We invite submissions of papers on all aspects of innovative technology and application aspects of actuators and manipulation are welcome. We especially welcome discussions and demonstrations of implemented systems. Oral and poster presentations will be given. Particular topics of interest include, but are not limited to:

- smart materials
- piezoelectric actuation
- thermal actuation
- optical actuation
- optical sensor and actuator integration
- micro-mirrors
- nanopositioning equipment
- micro/nano-manipulators
- distributed actuation
- artificial muscles
- micro-valves
- micro-pumps

- scanning probe microscopy
- industrial and commercial developments and applications
- electromagnetic/magnetic actuation
- SMA actuation
- actuator for microoptics
- optical micro-manipulation
- optical switches/ relays
- actuation for light modulation
- micro/nano-actuators
- micro-robot
- next generation robotic manipulators
- actuation for optical/medical devices
- energy-efficient manipulation strategies
- actuation for disk storage devices
- phase-shift microscopy.

Invited Sessions:

Invited sessions are aimed at providing focused discussion on new and timely research topics, and innovative issues on optomechatronics. Each invited session will consist of at least four papers, which will be reviewed through the regular reviewing process. Those interested in organizing an invited session should contact the conference chair, **Professor Shun'ichi Kaneko (Hokkaido University, Japan)**, kaneko@ssi.ist.hokudai.ac.jp, by July 12, 2005, and submit a proposal including the list of contribution papers and a session title.

The symposium will consist of five coherent conferences as follows:

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IMPORTANT DATES

Abstract Due Date: 18 July 2005

**Manuscript Due Date:
26 September 2005**

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Call for Papers

Optomechatronic Sensors and Instrumentation (JOM102)

Conference Chair: **Yasuhiro Takaya**, Osaka Univ. (Japan)

Cochairs: **Akira Ishii**, Ritsumeikan Univ. (Japan); **Takayuki Tanaka**, Hokkaido Univ. (Japan); **TaeHo Ha**, Korea Institute of Machinery & Materials (South Korea); **Jonathan Kofman**, Univ. of Waterloo (Canada)

Program Committee: **Young June Cho**, Korea Institute of Science and Technology (South Korea); **Sangsoo Choi**, LG Electronics Inc. (South Korea); **Terutake Hayashi**, Osaka Univ. (Japan); **Hideki Ina**, Canon Inc. (Japan); **George K. Knopf**, The Univ. of Western Ontario (Canada); **Hiroki Shimizu**, Tohoku Univ. (Japan); **Satoru Takahashi**, The Univ. of Tokyo (Japan)

The novel achievements in optics, semiconductors, micro-machines, and micro-system technologies significantly enhance the requirements for highly precise and efficient sensors and instrumentation. Furthermore, for the tremendous developments in the rapidly increasing field of nanotechnology, a tight link between electro-optical components and mechanical systems becomes essential. This conference will focus on recent developments in sensors, instrumentation, and their applications in the engineering field of optomechatronic technology emerging from the integration and functional fusion of optical and mechatronic engineering. It brings together engineers and researchers seeking solutions for their particular optomechatronic problems. The conference program will consist of oral and poster presentations on topics that include, but are not limited to:

- metrology for microtechnology and nanotechnology
- microstructure measurement
- shape measurement/reverse engineering
- large-area and aspheric surface inspection
- accurate roundness, cylindricity, and diameter measurement
- coordinate measuring machine (CMM) measurement
- sensing and measurement in positioning stage systems
- precision angle measurement
- wavelength or optical frequency measurement
- measurement of environmental influences
- refractive index of air correction
- non-destructive evaluation of structures
- calibration and standardization in optical metrology
- calibration standards and uncertainty evaluation
- surface quality control and material research
- characterization of nanostructured functional surfaces and modeling procedures
- nanotopography and roughness measurement
- particle, defect, flow analysis, and sub-surface detection
- film thickness measurement

- light scattering techniques (BSDF; Total Scatter etc.)
- Fourier transform (FT) instruments
- Interferometry, photogrammetry, liquid crystals, infrared sensing
- holographic and speckle techniques
- fiber optic sensors
- short- or partial-coherence interferometry
- fiber gratings
- photonic crystal circuits for integrated optics
- novel applications of near-field optics
- near-field enhancements of plasmonic imaging or sensing.

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Optomechatronic Micro/Nano Devices and Components (JOM103)

Conference Chair: **Yoshitada Katagiri**, Nippon Telegraph and Telephone Corp. (Japan)

Cochairs: **Eiji Higurashi**, The Univ. of Tokyo (Japan); **Katsuo Kurabayashi**, Univ. of Michigan; **Pamela R. Patterson**, HRL Labs.; **Akiko Gomyo**, NEC Corp. (Japan); **Ichirou Ishimaru**, Kagawa Univ. (Japan); **Kazuo Hotate**, The Univ. of Tokyo (Japan); **Bradley J. Nelson**, ETH Zürich (Switzerland)

Program Committee: **Kazuo Aida**, Shizuoka Univ. (Japan); **Andres Fernandez**, Glimmerglass; **Terunao Hirota**, The Univ. of Tokyo (Japan); **Mikio Horie**, Tokyo Institute of Technology (Japan); **Sang-Gook Kim**, Massachusetts Institute of Technology; **Horacio Lamela**, Univ. Carlos III de Madrid (Spain); **Takashi Matsuoka**, Tohoku Univ. (Japan); **Yasuyuki Mitsuoka**, Seiko Instruments Inc. (Japan); **Mitsuru Naganuma**, Teikyo Univ. of Science and Technology (Japan); **Masashi Nakao**, NTT Photonics Labs. (Japan); **Luis R. Nunes**, National Institute of Information and Communications Technology (Japan); **Toshifumi Ohkubo**, Toyo Univ. (Japan); **Kazuhiro Oiwa**, National Institute of Information and Communications Technology (Japan); **Fumikazu Oohira**, Kagawa Univ. (Japan); **Metin Sitti**, Carnegie Mellon Univ.; **Shuichi Takeda**, Applied Diamond Inc. (Japan); **Hakan Urey**, Koç Univ. (Turkey); **Katsuyuki Utaka**, Waseda Univ. (Japan); **Manabu Yamamoto**, Tokyo Univ. of Science (Japan)

At this very young stage of the twenty-first century, the emergence of a novel stream is expected to be seen in nanoscale technologies dealing with small objects, including atoms and molecules to establish a sophisticated information-oriented society with some epoch-making innovations, which may include novel computers equivalent to human brains. Although the expectation is supported by many technological sprouts in a wide variety of fields including telecommunications, information processing, and sensing, we are still faced with some critical issues that include how the diffraction limit is overcome or how optical signals are stored against the theory of relativity. For success in a continuing mission to improve science and technologies for the society of the future, it is due time to move on to discussing ways of overcoming such issues. Researchers and engineers will have an opportunity to exchange their opinions in this interdisciplinary conference. Papers on all aspects of the topics are welcome, including, but not limited to, the following:

- micro/nano mechaphotonics and applications including MEMS/NEMS devices, components, and sub-systems for data storage, communications, and network sensing
- nanophotonic active/passive devices and related physics including quantum and optical non-linear effects
- nano-bio mechanics and medical engineering including manipulation of atoms and molecules
- nanofabrication technologies including micro/nano processing, nano-imprinting, and homo/hetero splicing
- novel computer architectures based on quantum mechanics or molecular biology.

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Optomechatronic Machine Vision (JOM104)

Conference Chair: **Kazuhiko Sumi**, Kyoto Univ. (Japan)

Cochairs: **Hiroyasu Koshimizu**, Chukyo Univ. (Japan); **Yeong-Ho Ha**, Kyungpook National Univ. (South Korea); **Jonathan Kofman**, Univ. of Waterloo (Canada); **Claudio A. Perez**, Univ. de Chile (Chile)

Program Committee: **John Billingsley**, Univ. of Southern Queensland (Australia); **Didier Coquin**, Univ. de Savoie (France); **Seiji Hata**, Kagawa Univ. (Japan); **Dieter Just**, Eumetsat (Germany); **Yukio Sato**, Nagoya Institute of Technology (Japan); **Jun'ichi Yamaguchi**, Kagawa Univ. (Japan)

Machine vision technology, which originates from industrial robot vision and automated inspection, is now widely used in research and industry. Recent progress of sensors and processors has achieved higher performance of machine vision, which is in many applications far beyond human vision in terms of sensitivity, precision, and processing speed. Machine vision is a key technology of automation. In particular, optical sensing and information processing of sensor data are now pioneering a new technological world, overcoming the shortcomings of conventional TV cameras and electronic image processing. This conference will focus on proposals, principles, and applications related to sensing and information-processing technology of machine vision, and speakers and participants will exchange their latest knowledge. Particular topics of interest include, but are not limited to:

- sensing technology for machine vision including optics, illuminations, image sensors, devices, and measurement methods
- imaging technology including range imaging, stereo, surface analysis, particle analysis, defect analysis, and other measurements
- integration of sensing technologies including multi-sensor fusion, and multi-view analysis
- information processing for optomechatronic sensory data
- applications including automation, robotics, vehicle control, visual inspection, and human interface
- development environments and tools.

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Optomechatronic Systems Control (JOM105)

Conference Chair: **Farrokh Janabi-Sharifi**, Ryerson Univ. (Canada)

Cochairs: **Toshio Fukuda**, Nagoya Univ. (Japan); **Frank L. Lewis**, The Univ. of Texas at Arlington; **Wei Gao**, Tohoku Univ. (Japan); **Hyung Suck Cho**, Korea Advanced Institute of Science and Technology (South Korea)

Program Committee: **George Barbastathis**, Massachusetts Institute of Technology; **Francois Chaumette**, Institut National de Recherche en Informatique et en Automatique (France); **Iraj Hassanzadeh**, Ryerson Univ. (Canada); **Chih-Kung Lee**, National Taiwan Univ. (Taiwan); **Cheng-Hsien Liu**, National Tsing Hua Univ. (Taiwan); **Bradley J. Nelson**, ETH Zürich (Switzerland); **Yves-Alain Peter**, École Polytechnique de Montréal (Canada); **Masatake Shiraiishi**, Ibaraki Univ. (Japan); **Bruno Siciliano**, Univ. degli studi di Napoli Federico II (Italy)

Optomechatronic control systems deal with the control of integrated optical and mechatronic systems to achieve high performance and functionality, such as high precision, rapid information processing, and intelligent functions. Based on the integration method, optomechatronic control systems could be classified into: optically embedded mechatronic systems, mechatronically embedded optical systems, and optomechatronically fused systems. These control systems offer significant potential advantages over the conventional control systems in terms of power, signal attenuation, bandwidth, flow of information, electromagnetic interference immunity, and safety. However, control of optomechatronic systems involves serious challenges due to inherent system non-linearities, uncertainties, time-varying properties, and disturbances. Addressing such control problems is vital for future advancement and the advent of new applications of optomechatronic technology. In order to strengthen the science and engineering of opto-mechatronic control systems, it is essential that researchers and engineers communicate and coordinate their work. The purpose of this conference is to promote research activities in various areas of design and implementation of optomechatronic control systems by providing a forum for the exchange of ideas, presentation of technological achievements, and discussion of future directions. Particular topics of interest include, but are not limited to:

- modeling
- estimation and identification
- automated navigation
- motion control
- robot control
- guidance and flight control
- vibration and noise control
- computer network control
- process control

- vehicle and transportation control
- consumer electronics control
- medical equipment control
- bio-systems control
- virtual reality systems control
- teleoperation
- industrial automation
- synergistic control design methodologies
- control interface design
- emerging control technologies
- micro systems (MEMS) control
- IC-embedded control
- control signal transmission
- open architectures
- intelligent control
- learning control
- robust control
- hybrid systems
- rapid prototyping
- control education.

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Information concerning hotel reservations, as well as a hotel reservation form, will be included in the Technical Program available online in late September 2005.

Registration

The registration form for conferences will be available in the Technical Program.

Technical Program

Available online in late September 2005

The comprehensive Technical Program for this symposium will list conferences, paper titles, and authors in order of presentation; an outline of all planned special events; and information detailing the hotel reservations process.

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For those authors who need to obtain a Visa, remember to allow a minimum 2 months for processing and receiving.

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Submissions imply the intent of at least one author to register, attend the symposium, present the paper as assigned (either orally or in poster format), and submit a full-length manuscript for publication in the conference Proceedings.

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SUBJECT: Conf. Code (example: jom101)

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- 1. PAPER TITLE**
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- 3. PRESENTATION PREFERENCE** "Oral Presentation" or "Poster Presentation."
- 4. PRINCIPAL AUTHOR'S BIOGRAPHY** Approximately 50 words.
- 5. ABSTRACT TEXT** Approximately 250 words.
- 6. KEYWORDS** Maximum of five keywords.

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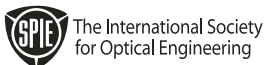
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- Applicants will be notified of abstract acceptance by e-mail no later than 29 August 2005, and manuscripts are due on 26 September 2005 from all accepted authors.
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